



MAVIS UPDATE: WFSING AND CONTROL

PRELIMINARY DESIGN STATUS

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MAVIS (AO) OVERVIEW

MCAO Assisted Visible Imager and Spectrograph

- 8 LGS 40x40 SHWFS,
- Up to 3 NGS: 1x1 or 2x2 SHWFS
- 3 DMs:
 - VLT UT4 DSM @ 0 km,
 - ALPAO DM3228 @ 6.5 km,
 - ALPAO DM3228 @ 13 km.

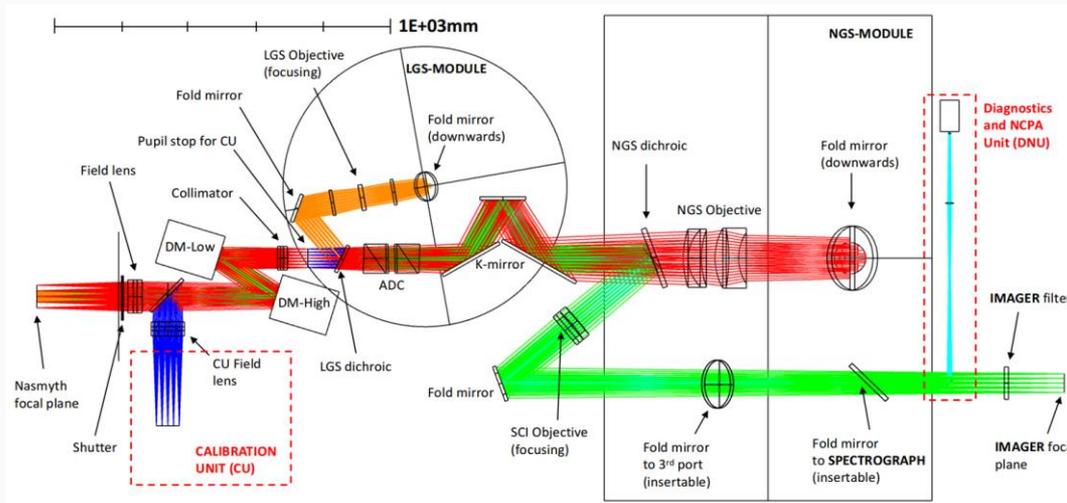


Figure 1: MAVIS optical path

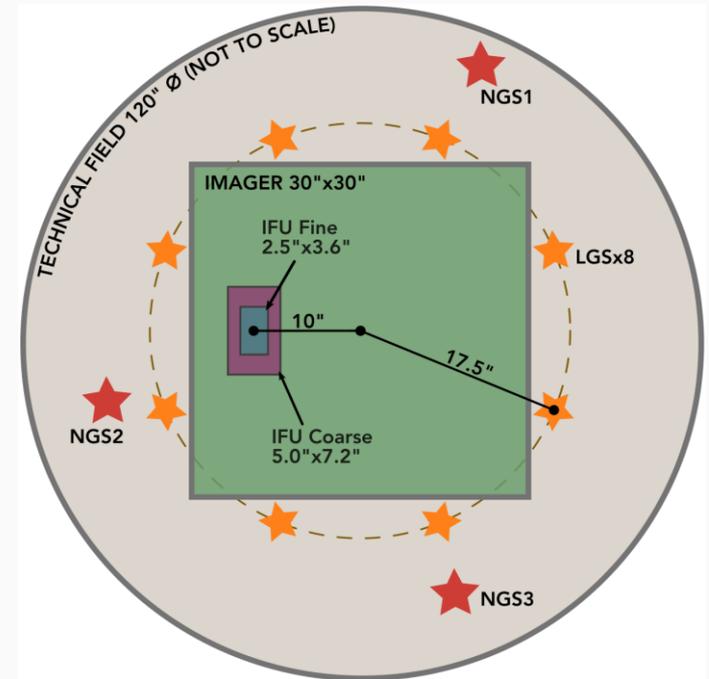


Figure 2: MAVIS field of view

MAVIS FUN* STUFF:

- Super-resolution LGS WFSing optimisation,
- Tomographic NCPA calibration,
- Real-time atmospheric profiling,
- 1x1/2x2 switchable NGS WFSing,
- Control schemes:
 - Predictive Learn & Apply (PL&A),
 - Minimum Mean Square Error (MMSE),
 - Linear Quadratic Gaussian (LQG).
- LGS jitter control,
- And more...

*subjective

SUPER-RESOLUTION WFSING

- Diversity in WFSs improves AO performance,
- Automatically achieved for *most* layers, but not for ground layer,
- Rotating WFSs allows super-resolution on ground layer.

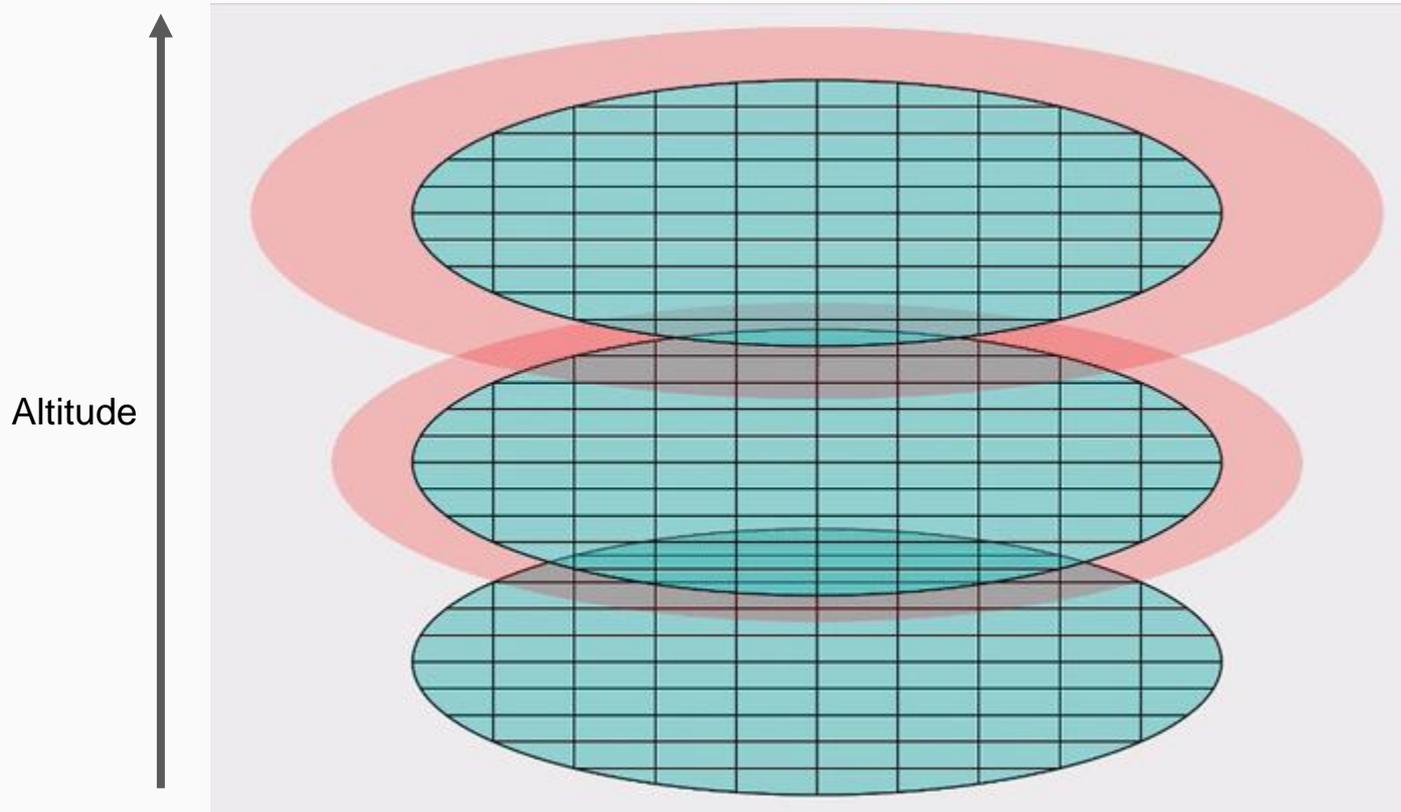


Figure 3: 2 SH-WFS in super-resolution

SUPER-RESOLUTION LGS WFSING

- MAVIS has 8 high order WFSs,
- Note: if it looks like a mess, it can sense well

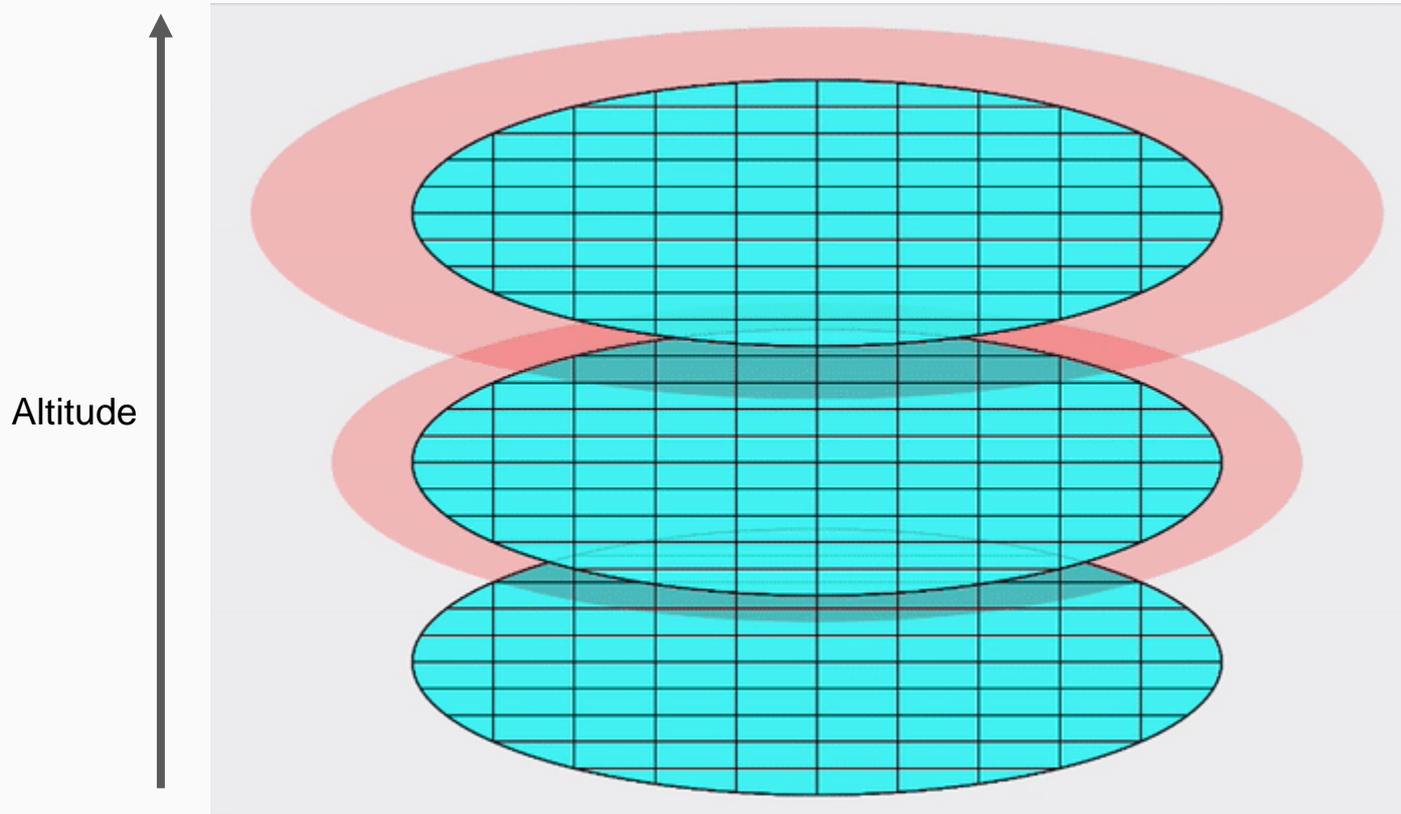


Figure 4: 8 SH-WFS in super-resolution

SUPER-RESOLUTION LGS WFSING

Maximum rotational diversity 😊 -> difficult to do mechanically 😞

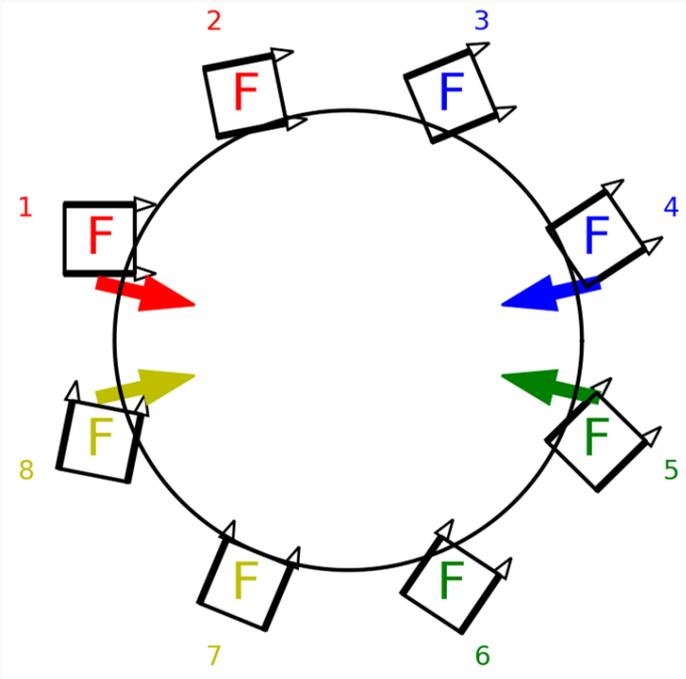


Figure 5: Ideal **super-resolution** alignment. Maximum rotational diversity (modulo $\pi/2$)

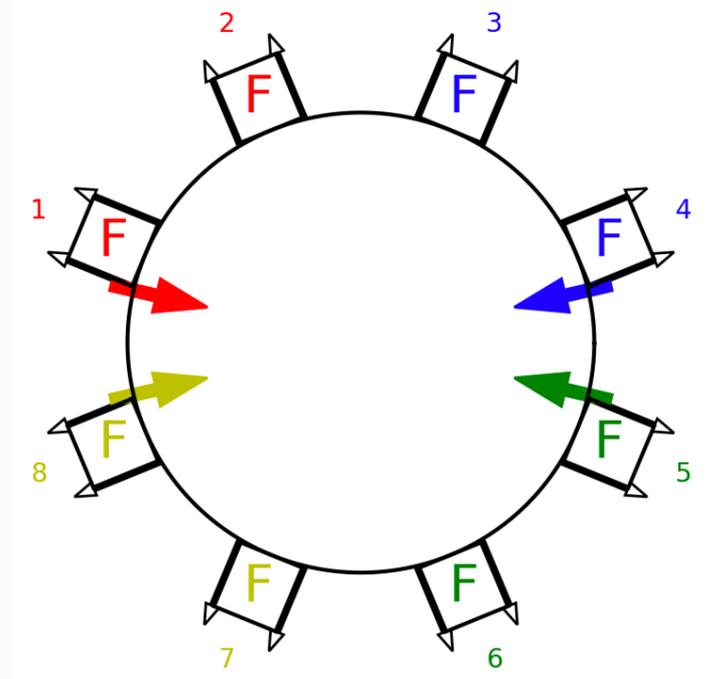


Figure 6: Ideal **mechanical** alignment. WFS cameras mounted radially, reduces volume of enclosure and simplifies cable routing.

SUPER-RESOLUTION LGS WFSING

But wait, there's more!

We can also minimise **LGS spot truncation** by rotating:

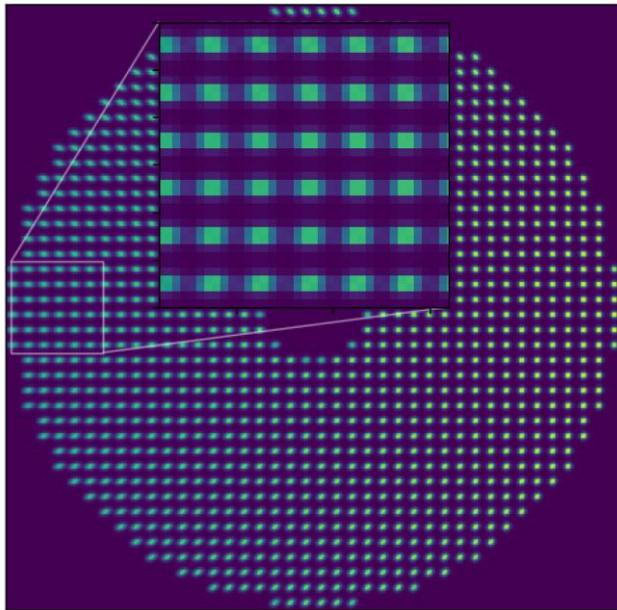


Figure 7: LGS elongation axis aligned with **short-axis** of SH spot array

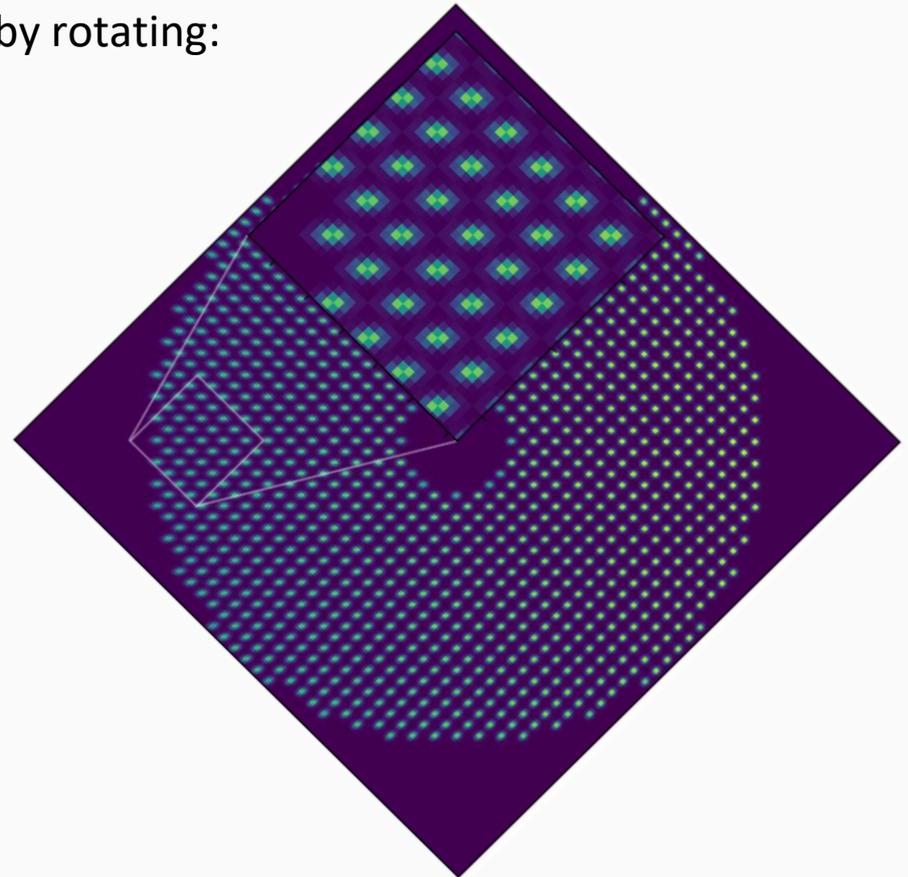


Figure 8: LGS elongation axis aligned with **long-axis** of SH spot array

SUPER-RESOLUTION LGS WFSING

So... we want to simultaneously optimise for:

- Maximum diversity,
- Simplest mechanical implementation,
- Minimal LGS spot truncation.

SUPER-RESOLUTION LGS WFSING

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Feeding these into a numerical optimiser gives:

**Wide field LE SR jumps from
24.7% -> 27.2% in V-band
(equiv: -27 nm RSS)**

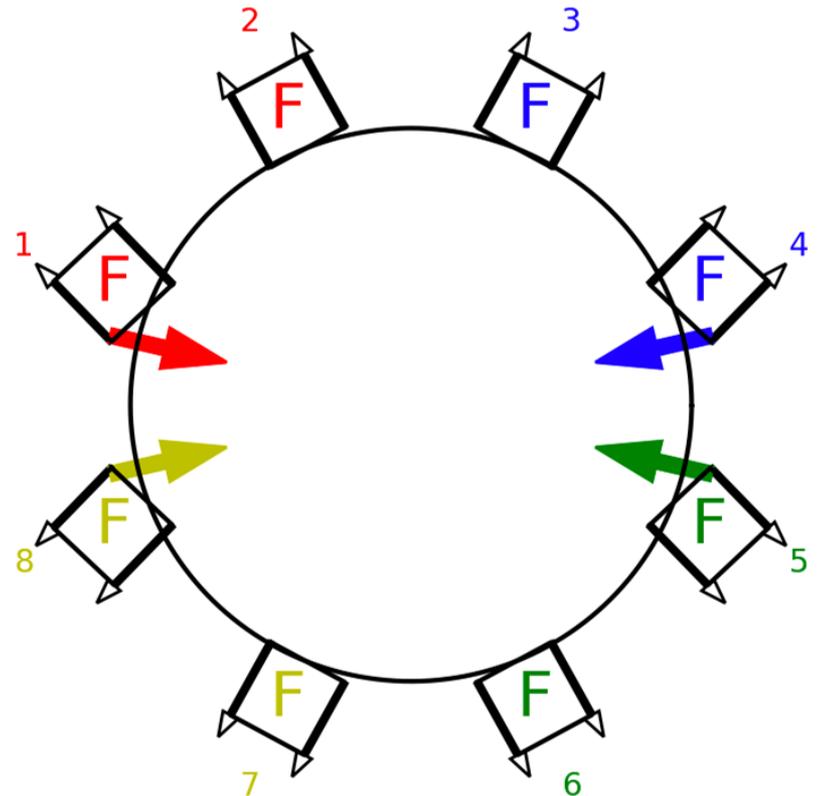


Figure 9: Final selection of LGS clocking angles to optimise all 3 criterion.
Coloured arrows indicate LGS elongation axes.

NCPAs in MAVIS

- Wide-field instrument + many surfaces -> field-varying static NCPAs
- Field-varying NCPAs + tight error budget -> tomographic phase diversity
- Method based on PRAy - Gratadour et al (2011)

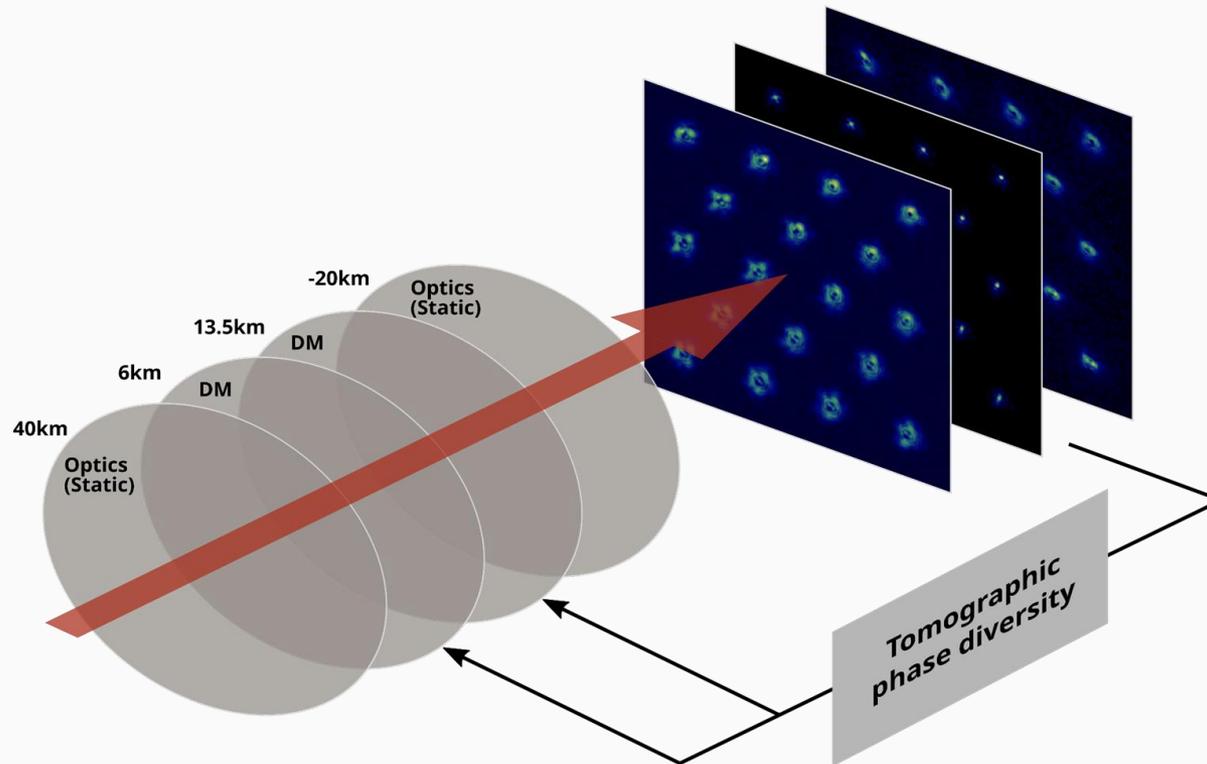


Figure 10: Tomographic phase diversity principle

NCPAs in MAVIS

- Requires many small sources over the science FoV (100 holes, each 5 μm ϕ),
- Test masks produced by Optofab in Sydney provide sufficient accuracy and throughput tested at Stromlo.

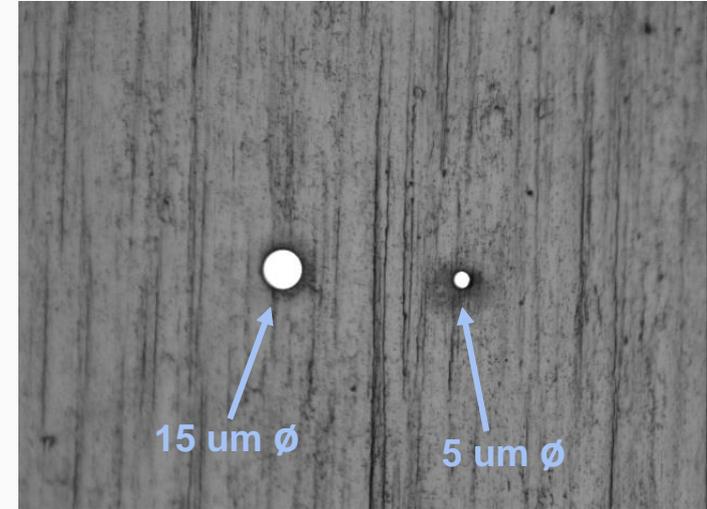


Figure 12: Pinholes under microscope

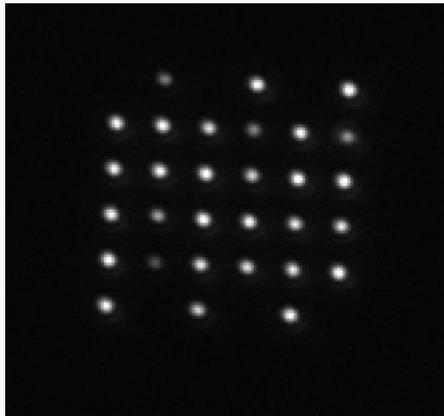


Figure 11: Image taken of 5 μm pinhole grid on the bench, pinholes are 40 μm apart.

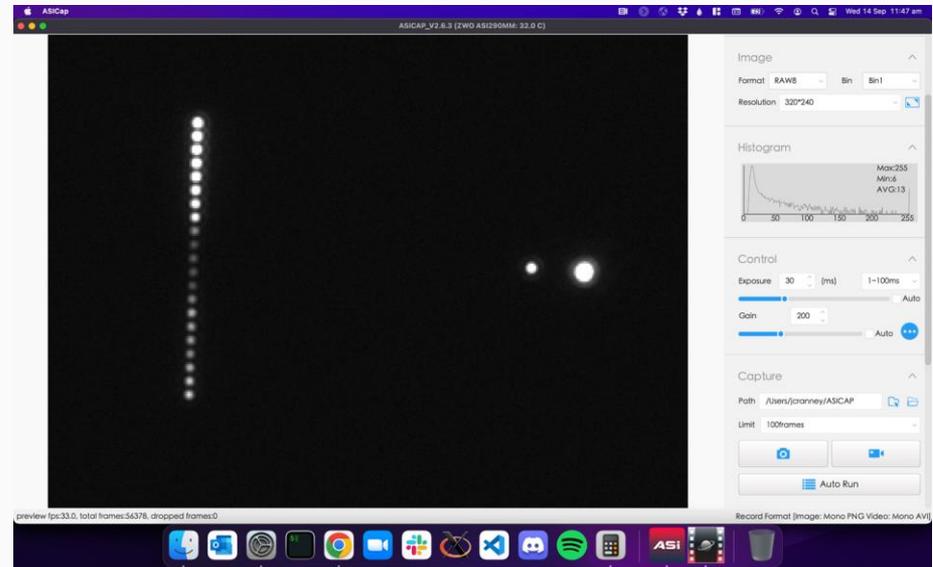


Figure 13: Imaged pinholes on the bench. (left) varying focus of cutting laser, (right) 5 μm and 15 μm pinholes.

NCPAs in MAVIS

- Simulations show we can converge on NCPA calibration with 64 sources simultaneously in less than 1 second on GPU,
- Prototyping in the lab for MAVIS commencing Q1 2023.

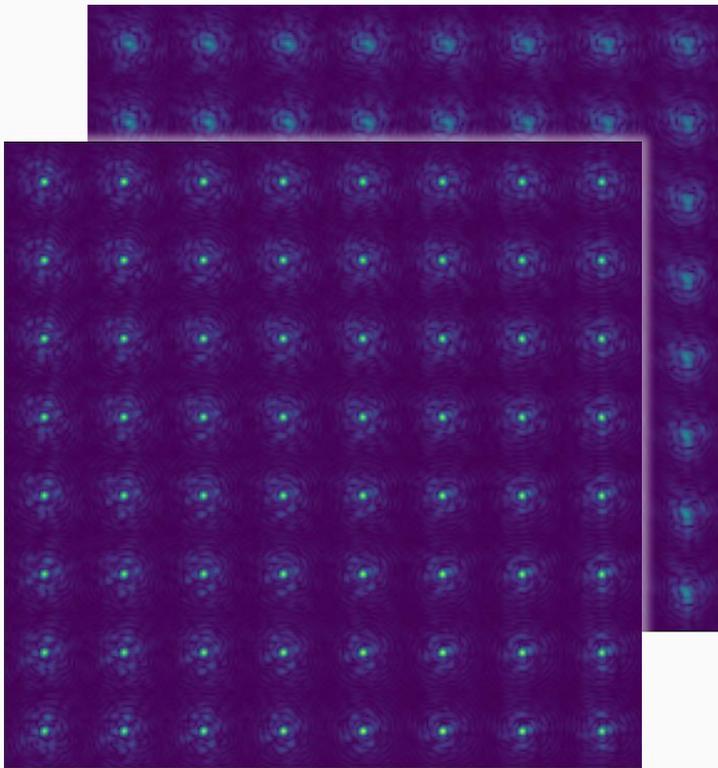


Figure 14: Simulated NCPA pinhole images

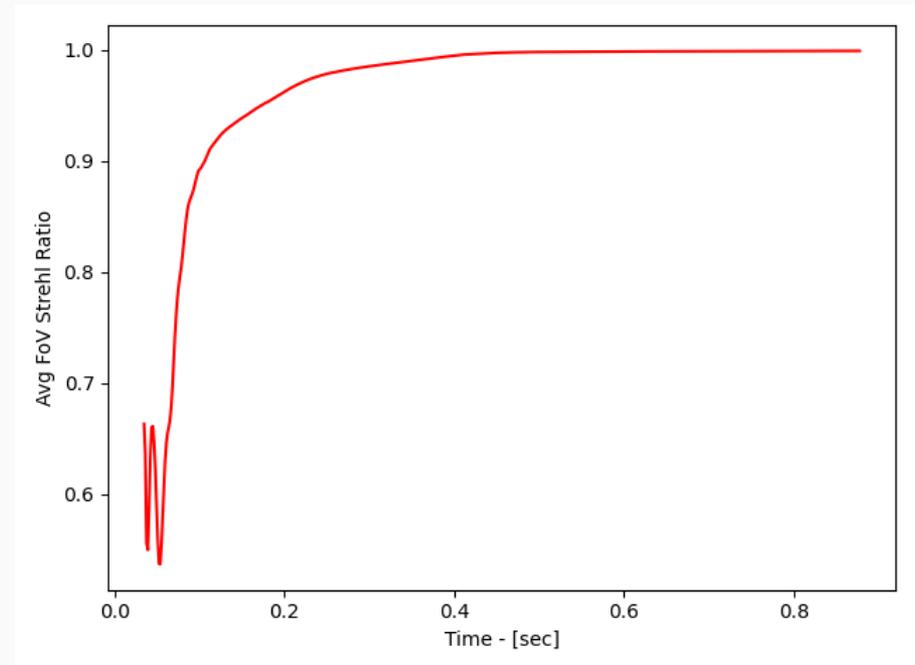
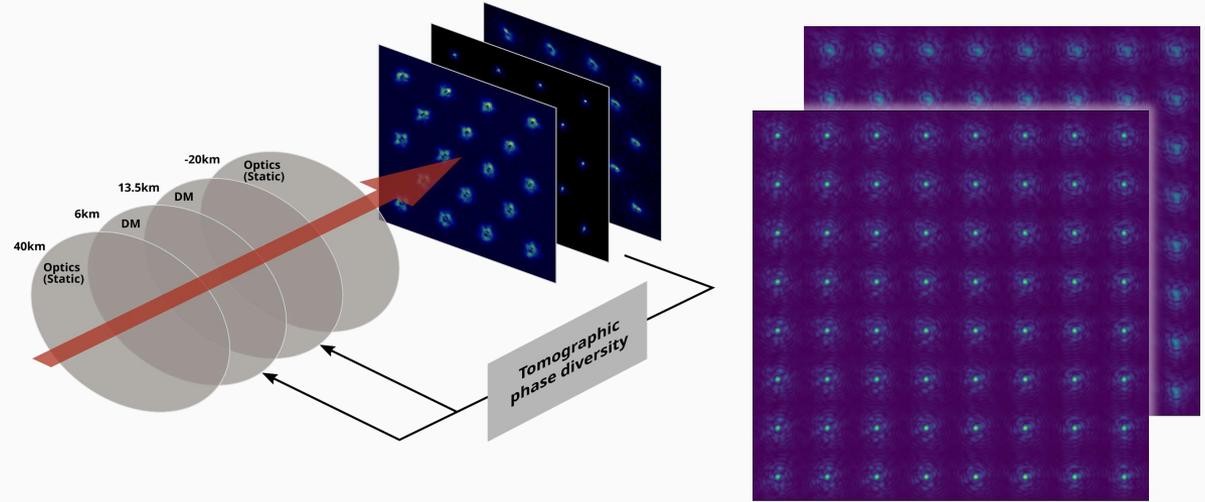
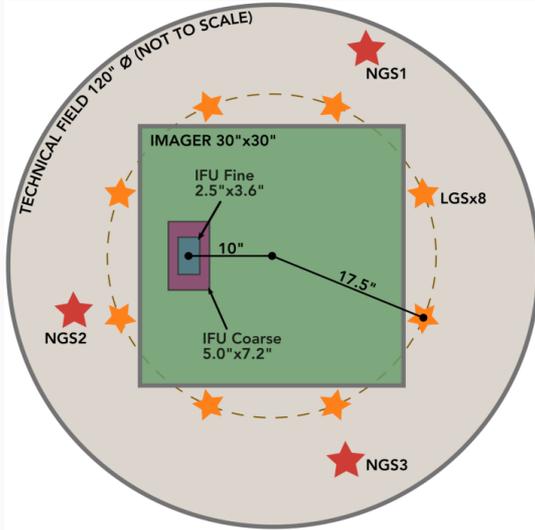


Figure 15: Tomographic phase diversity convergence vs time.

THANKS!



Questions?

