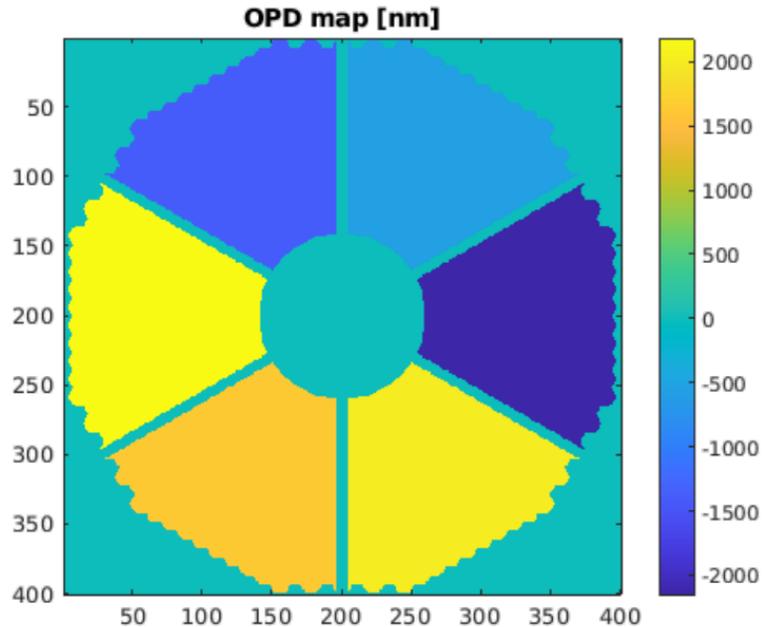


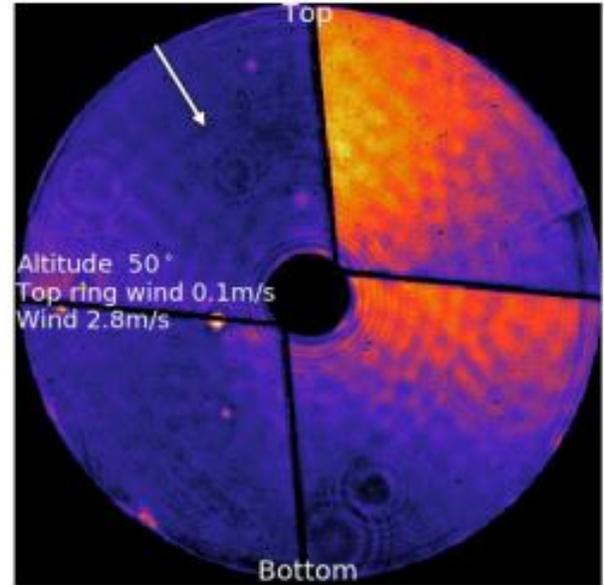
Dynamic, optical gain compensation and phase unwrapping for the Zernike Wave-Front Sensor

Mahawa CISSE, Vincent CHAMBOULEYRON, Olivier FAUVARQUE, Charlotte BOND,
Nicolas LEVRAUD, Jean-François SAUVAGE, Benoît NEICHEL, Thierry FUSCO

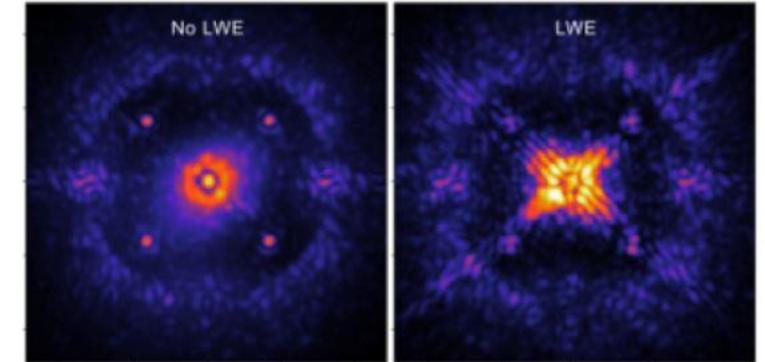
Context : High angular resolution with the ELTs



Differential piston



Low-Wind Effect (LWE)

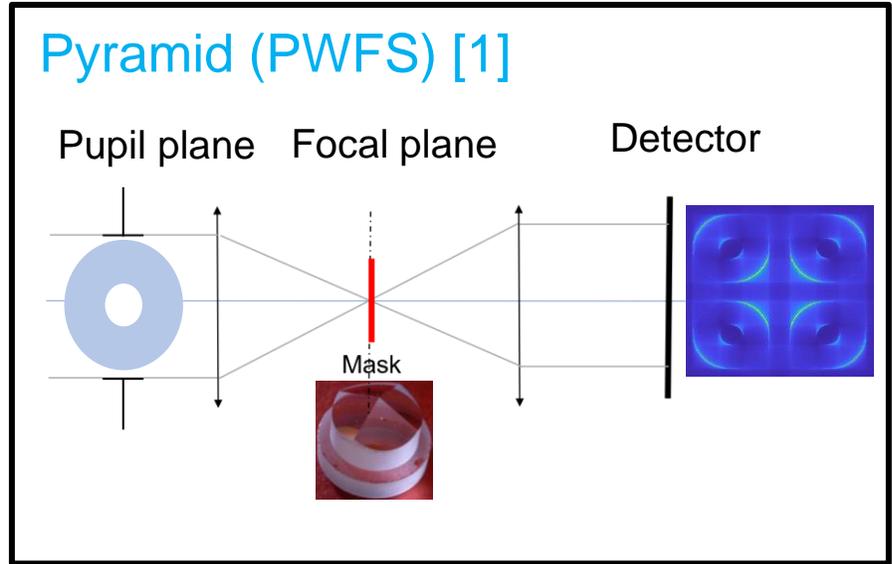
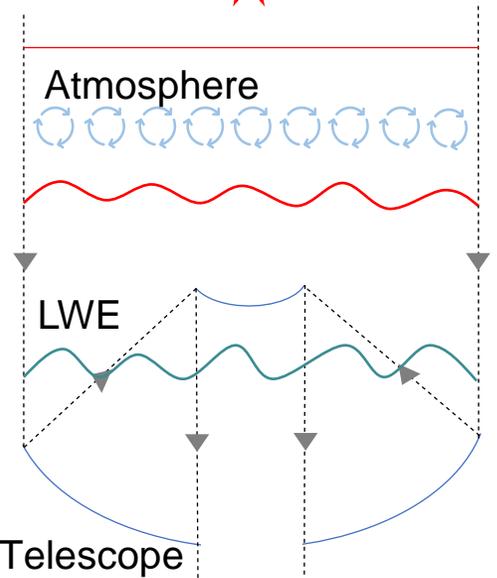


High contrast imaging

New challenges for Wave-Front Sensing (WFS) for Adaptive Optics (AO) systems to achieve high angular resolution

Reference :
Milli, J., et al 2018

Adaptive Optics and Wave-Front Sensing



- More sensitive than the Shack-Hartmann (SH)
- But highly non-linear sensor
→ modulation
- « Gradient sensor »
- **Modulated PWFS and SH are not sensitive to the petal mode or LWE**

- LWE measured by the ZELDA for the VLT as a 2nd stage correction cf Milli et al 2018

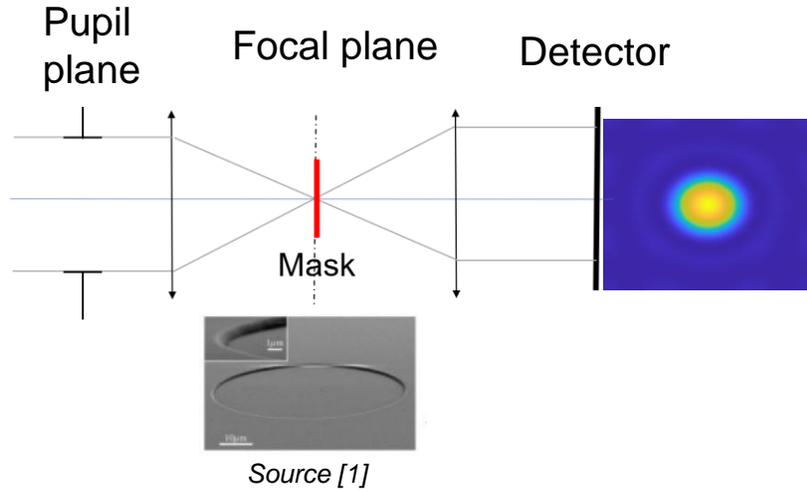
Need to analyse the Zernike WFS to measure aberrations

- Small phase → 2nd stage WFS, petalometer etc
- Large phase → AO WFS

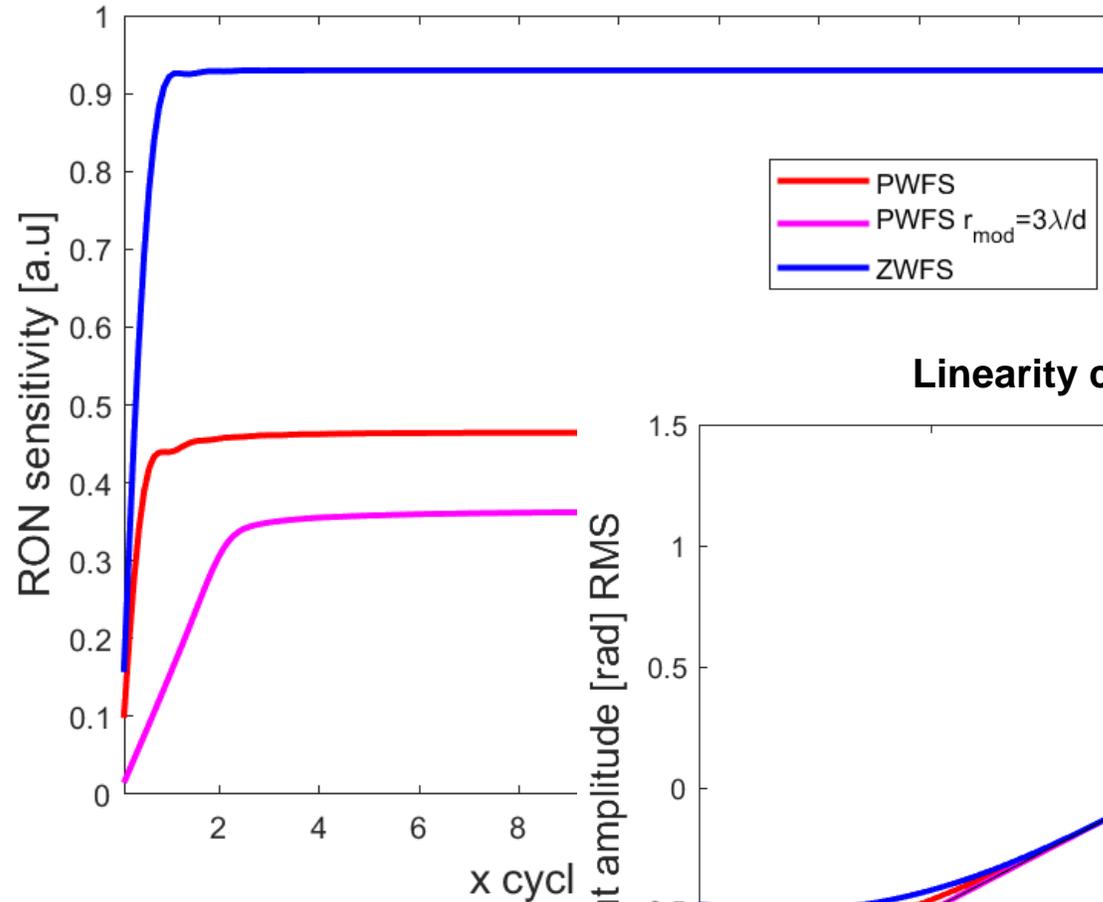
References :

[1] : Ragazzoni, R. (1996). Pupil plane wavefront sensing with an oscillating prism. *Journal of modern optics*, 43(2), 289-293.

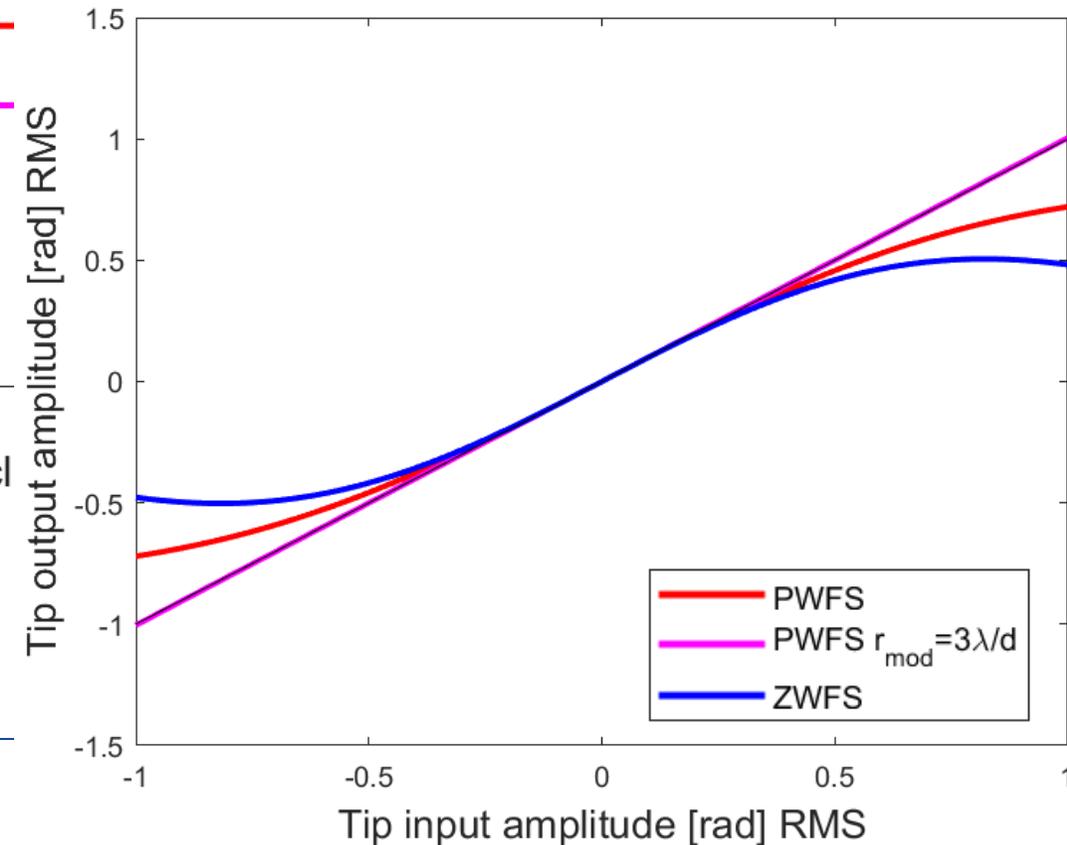
Zernike Wave-Front Sensor (ZWFS)



- More sensitive than the PWFS
- Phase sensor
- Less linear than the PWFS



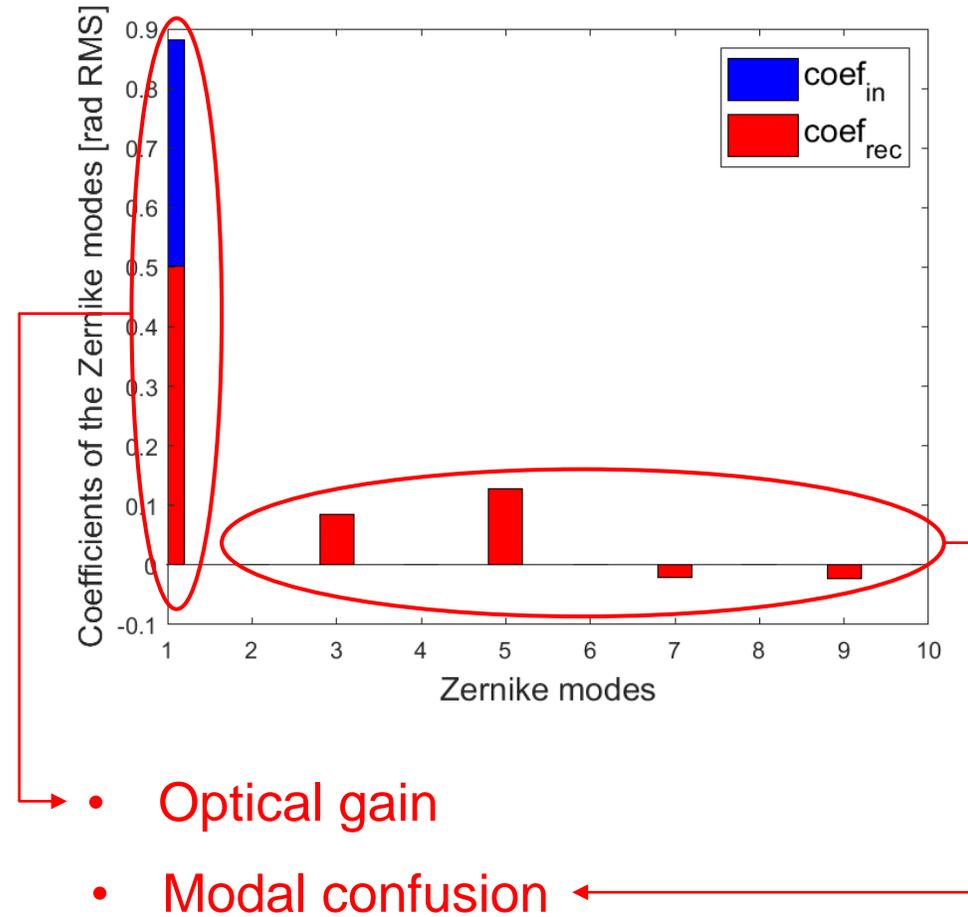
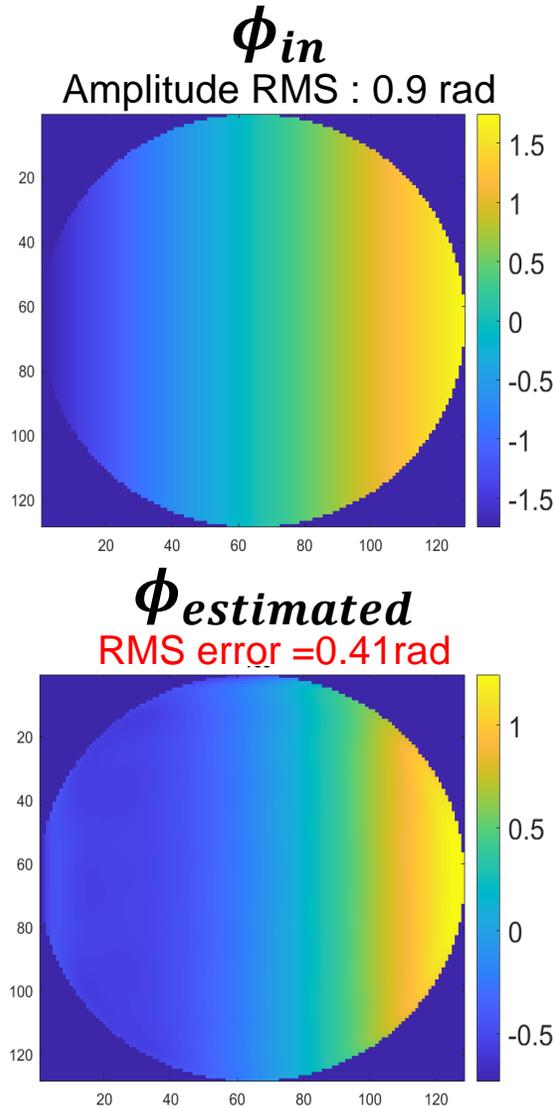
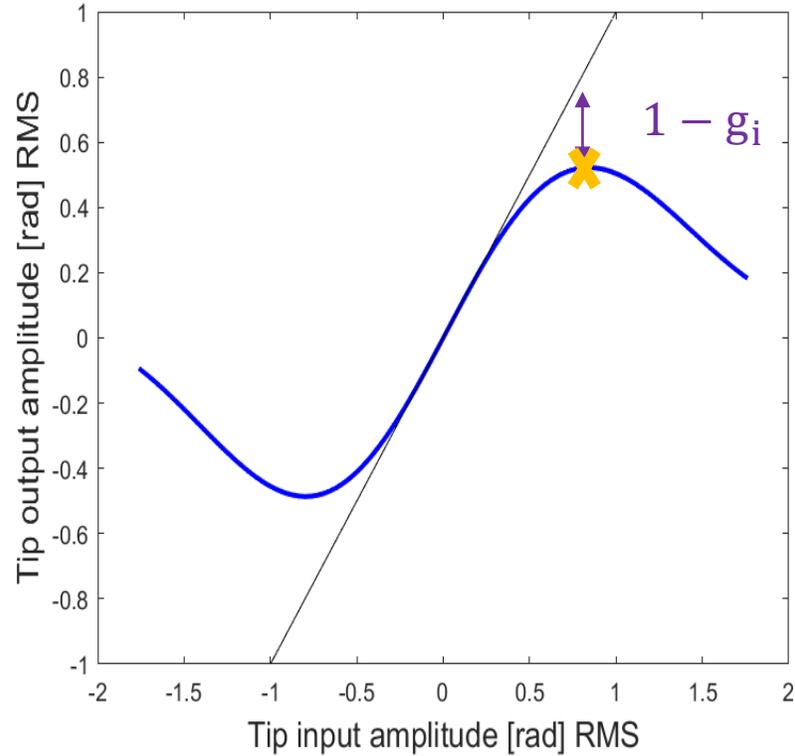
Linearity curves of FFWFS



References :

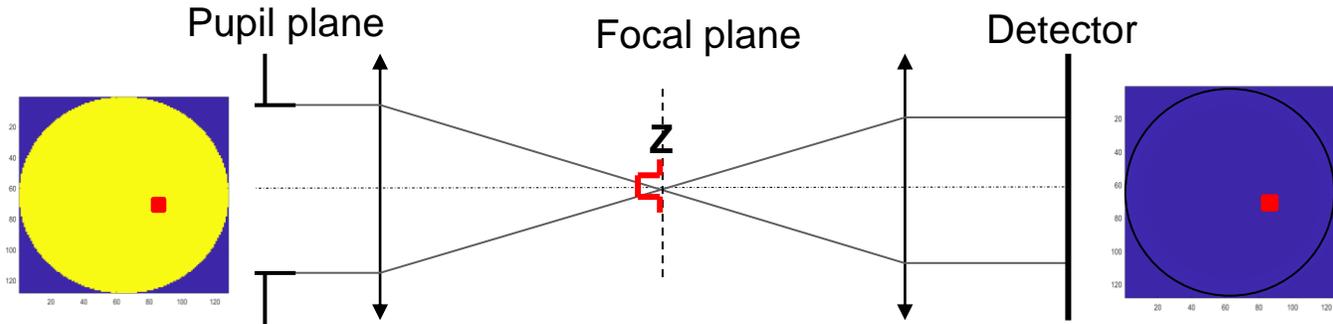
[1]: N'Diaye et al 2016

Non-linearities of the ZFWFS : Example with a Tip



Necessary to deal with the non-linear effects of the sensor

Phase reconstructors



Linear reconstructor :

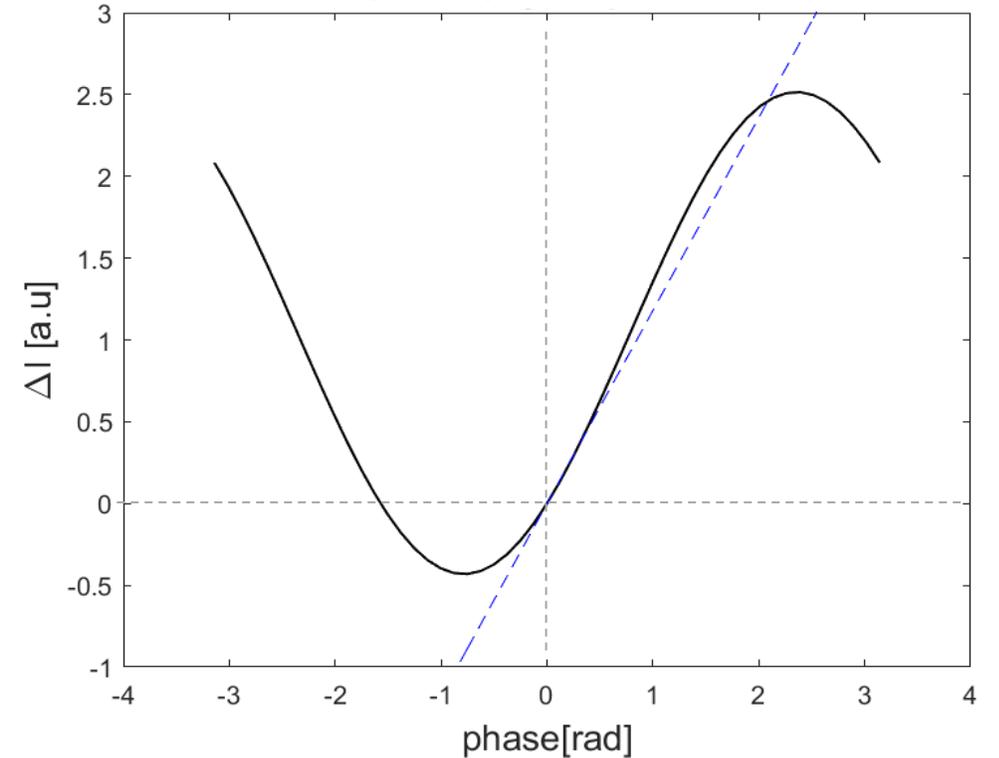
- $\varphi = \Delta I$

Matrix formalism :

- Calibration matrix $\varphi = D_c \Delta I$
- In presence of phase residuals $\varphi = D_{res} \Delta I$

$$D_{res} = (\delta I_{res}(Z_1), \dots, \delta I_{res}(Z_N)) \text{ with } \delta I_{res}(Z_i) = \frac{\Delta I(\Phi_{res} + \epsilon Z_i) - \Delta I(\Phi_{res} - \epsilon Z_i)}{2\epsilon}$$

Intensity response of one pixel



Optical gains computation

Matrix formalism :

- Calibration matrix D_c
- In presence of phase residuals D_{res}

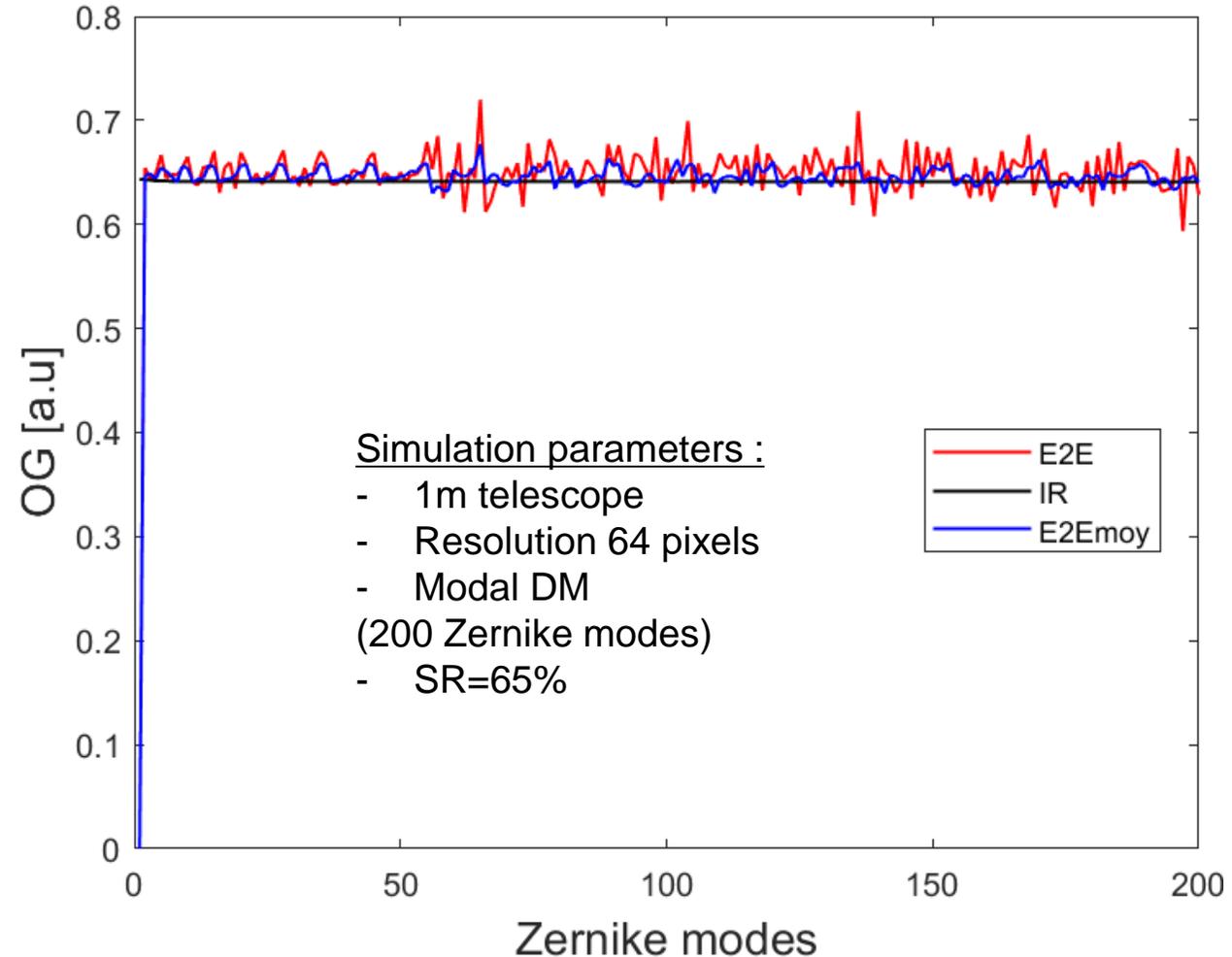
Hypothesis : $D_{res} = D_c T_\varphi$

Impulse response approach :

- At calibration : $IR_c = 2Im(\widehat{m}(\widehat{m} * \widehat{PSF}))$
- In presence of phase residuals : IR_{res}

$$\text{Optical gain : } g_i = \frac{\langle IR_{res} * \widehat{IR}_c | \varphi_i * \widehat{\varphi}_i \rangle}{\langle IR_c * \widehat{IR}_c | \varphi_i * \widehat{\varphi}_i \rangle},$$

$(\varphi_i)_{1 \leq i \leq n}$ modal basis



- **E2E & IR approach give the same OG**
- **OG independant of the modes $\rightarrow D_{res} = OG \cdot D_c$**

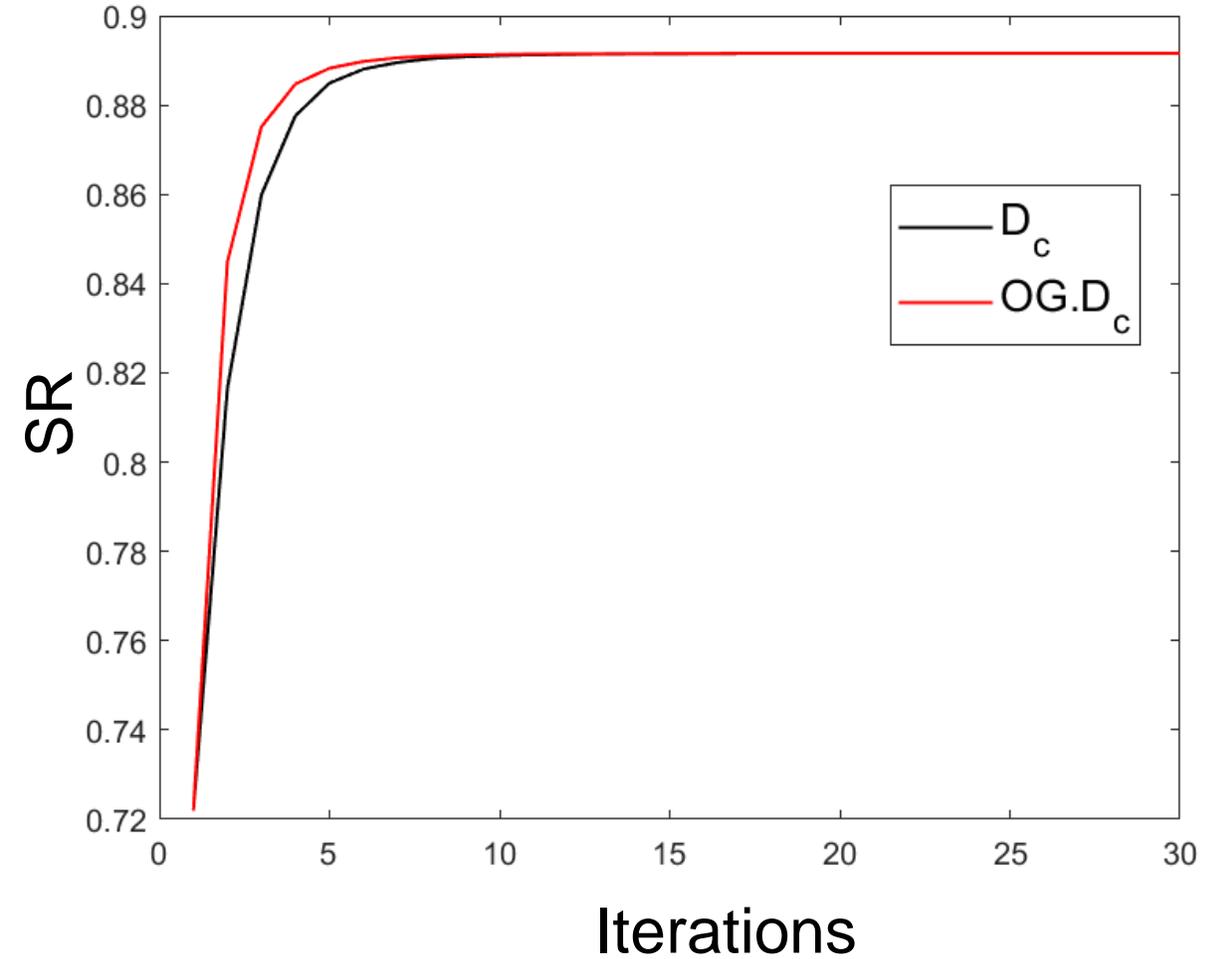
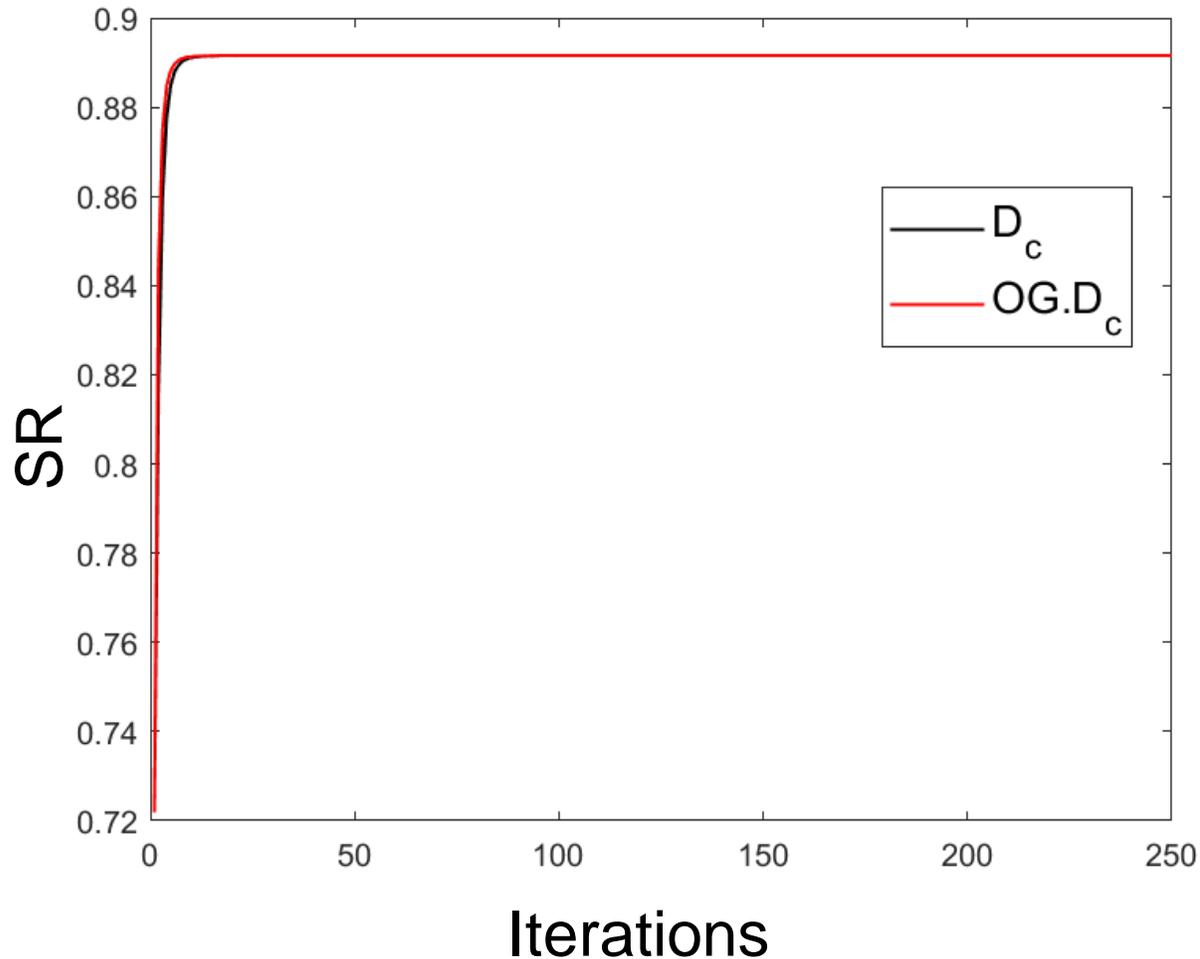
References :

- [1] : Chambouleyron, V. (2021). *PhD Thesis*
 [2] : Chambouleyron, V et al 2021

Simulation parameters :

- 1m telescope
- Resolution 64 pixels
- Modal DM
(200 Zernike modes)
- **SR=72%**

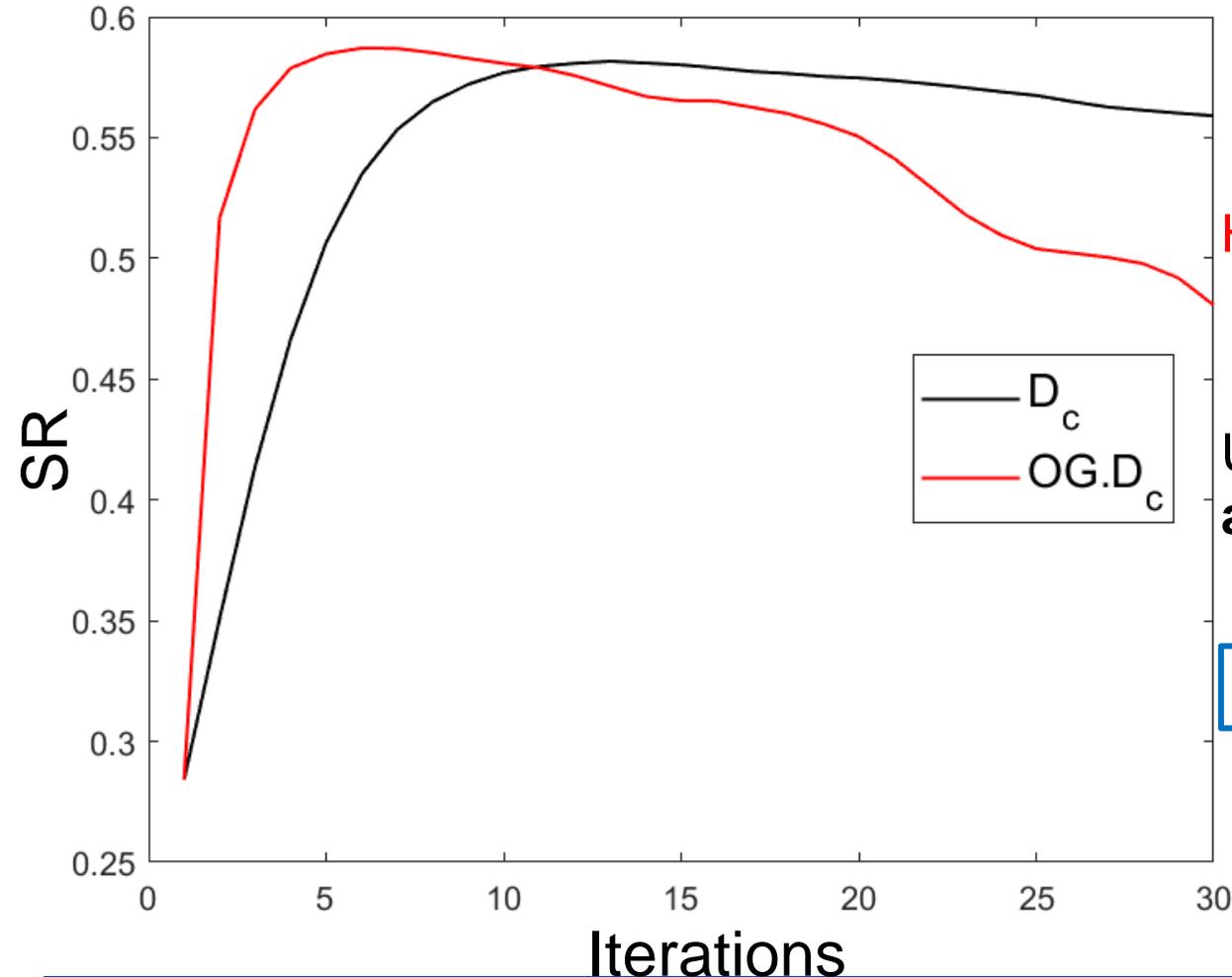
Close Loop test on phase residuals



Simulation parameters :

- 1m telescope
- Resolution 64 pixels
- Modal DM
(200 Zernike modes)
- **SR=29%**

Close Loop test : stronger turbulence



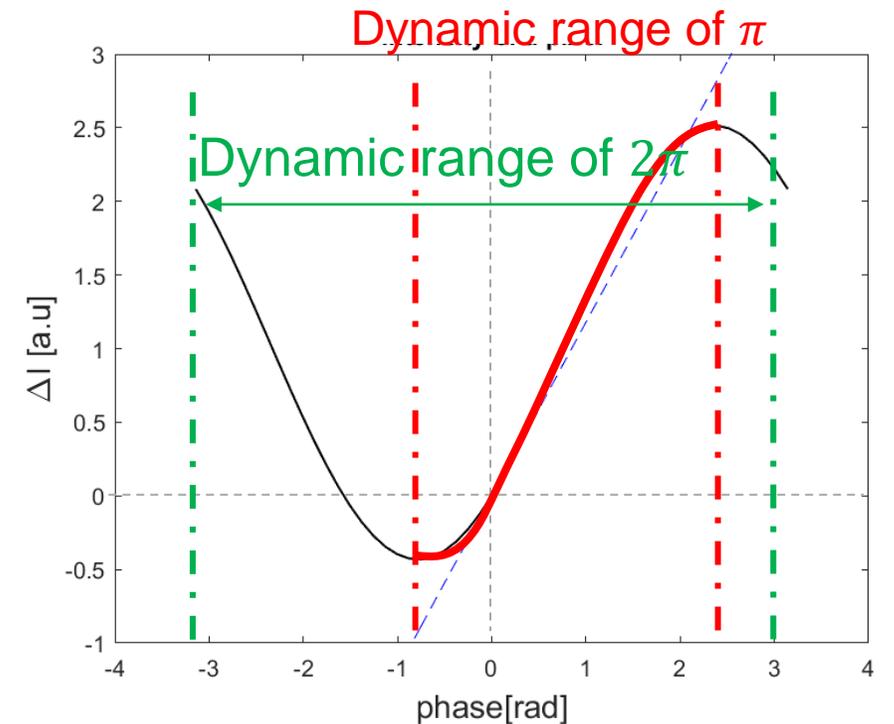
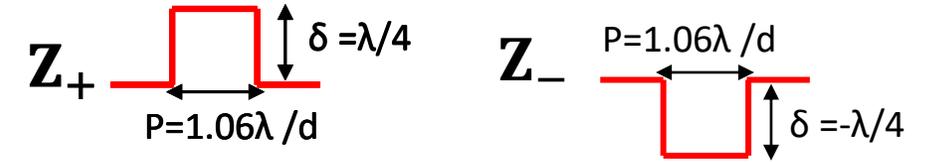
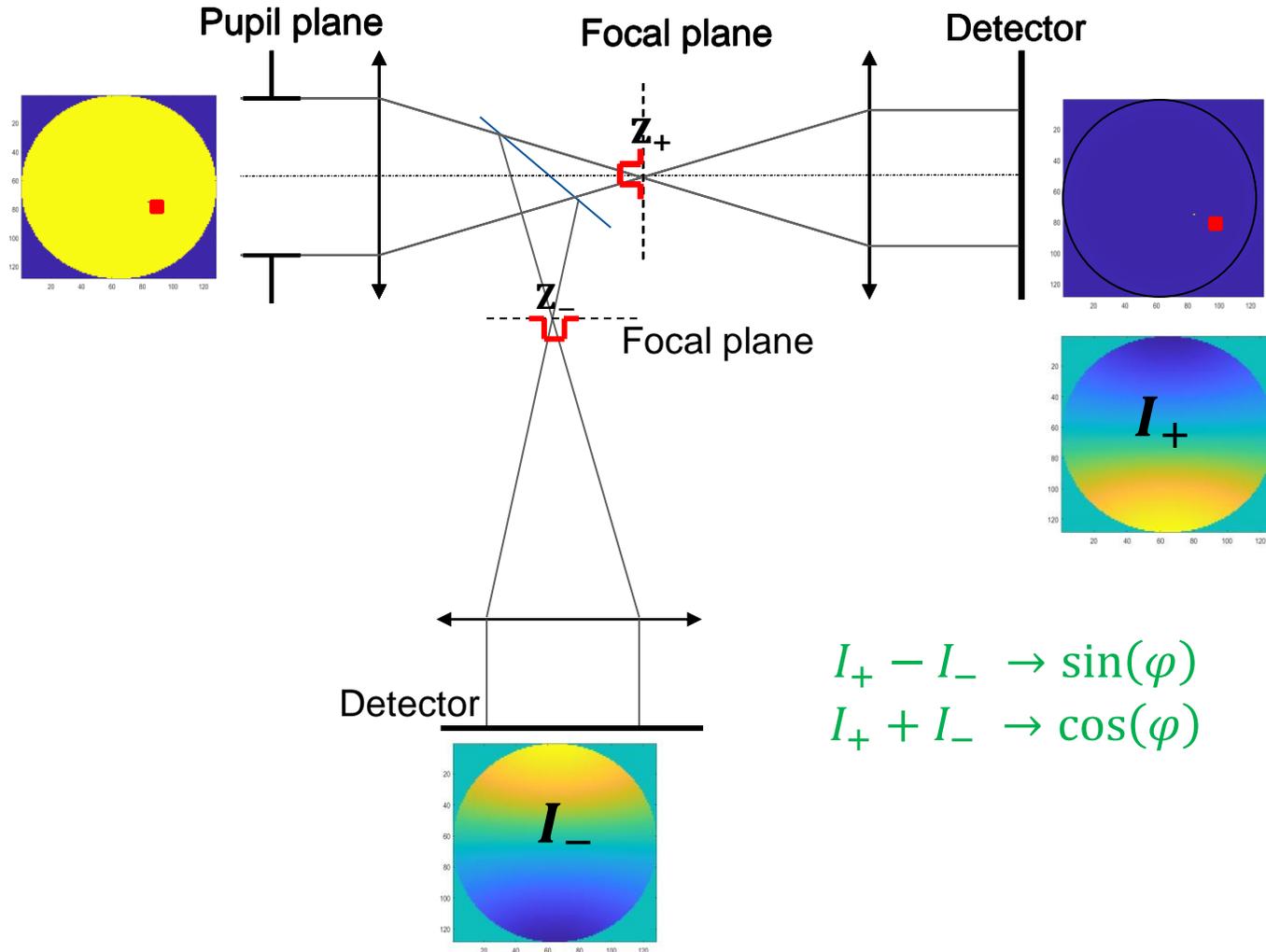
Hypothesis $D_{res} = OG.D_c$ no longer true

- Modal confusion has to be taking into account
→ non diagonal terms of T_φ

Use OG to modelize ZWFS response for **faint aberrations**

What about increasing the dynamic of the ZWFS

The Phase-Shifted ZWFS



Increased dynamic

Reference:
David S. Doelman et al (2019)

Review : ZWFS non-linearities & dynamic

- Use of OG limited by the phase residuals regime
- Modal confusion has to be taken into account
- Phase-Shifted ZWFS :
 - Increase the dynamic range
 - Less constraints on the phase residuals regime

On going work

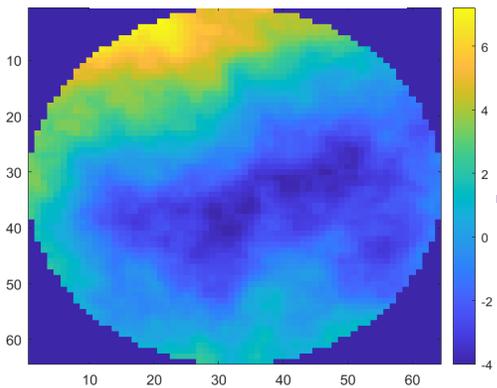
Can we bootstrap with the ZWFS?

ZWFS 1st stage AO: phase wrapping issues

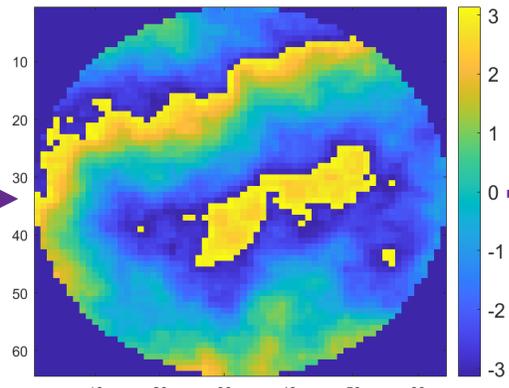
Easy part

What we want

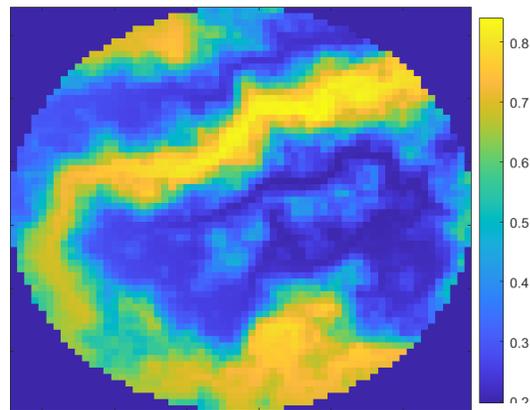
Input phase



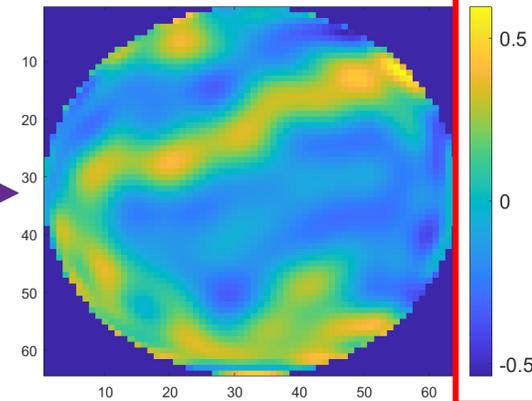
Phase seen by ZWFS



ΔI

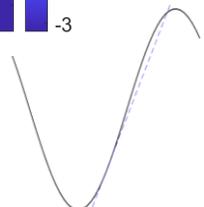


Phase estimated with D_c^\dagger



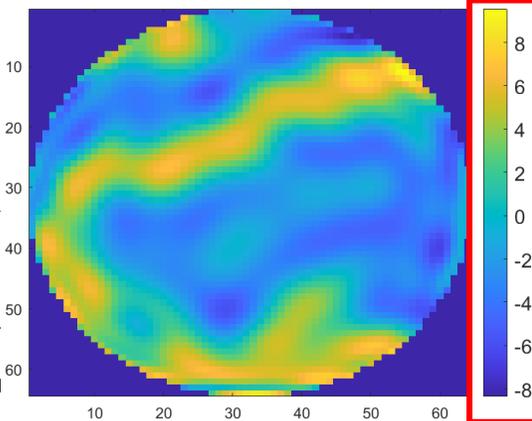
Modulo 2pi

ZWFS response



DM response

Phase estimated with D_c^\dagger / OG



Wavefront sensor

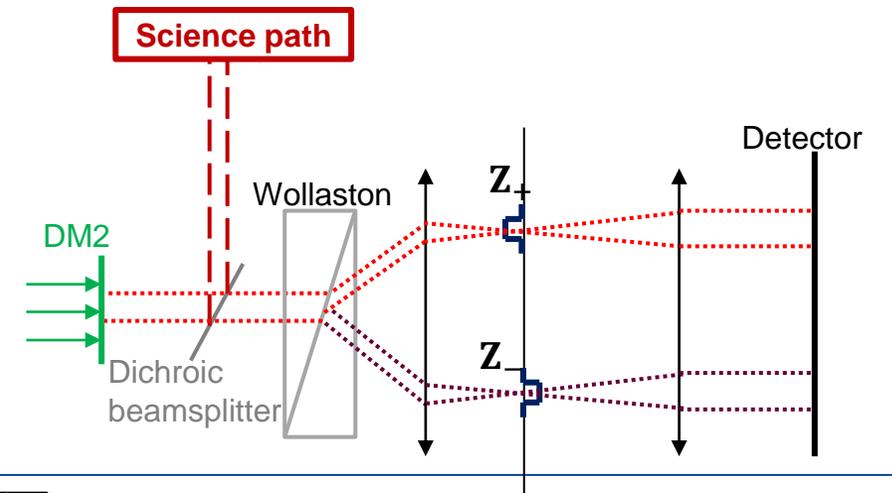
Conclusion

To have a better understanding of the non-linear behavior of the ZWFS to improve the phase estimation

- Using D_{res}^+ is the best approach to close the loop **BUT** not possible on sky
- ZWFS **strongly non-linear** → bias the phase estimation with the **classical phase reconstructors**
- **OG compensation is limited** because it does not take into account all the non-linear effect
- ZWFS give a **wrap phase estimation** when $\varphi > \pi$
- **Smoothing of the estimated phase** → **phase unwrapping not possible** with the classical unwrapping algorithm

Perspectives :

- Improve the dynamic range of the ZWFS → Phase-Shifted ZWFS
- Non-linear phase reconstructors



Thank you for listening

AO4 ELT - 7th Edition

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More information: Thierry.Fusco@onera.fr, Benoit.Neichel@lam.fr



Annexe 1 : Optical gains (OG)

- Matrix formalism : $\Delta I(\Phi) = D_c \Phi$ if $\Phi \ll 1$
- For large phase amplitude : $\Delta I(\Phi) = D_\Phi \Phi$ with $D_\Phi = D_c T_\Phi$
- T_Φ the matrix which describes the non linear regime : $T_\Phi = D_c^\dagger D_\Phi$

Reconstruction of the phase :

$$\begin{aligned}\Delta I(\Phi) &= D_\Phi \Phi \\ \Delta I(\Phi) &= D_c T_\Phi \Phi\end{aligned}$$

By using M_{com} computed during the calibration we have :

$$\hat{\Phi} = D_c^\dagger D_c T_\Phi \Phi = T_\Phi \Phi$$

- The optical gain g_i are on the diagonal of T_Φ
- Diagonal approximation : $g_i = \frac{\langle \delta I_{res}(\Phi_i) | \delta I_c(\Phi_i) \rangle}{\langle \delta I_c(\Phi_i) | \delta I_c(\Phi_i) \rangle}$, with $\delta I_{res}(\Phi_i) = \frac{\Delta I(\Phi_{res} + \epsilon \Phi_i) - \Delta I(\Phi_{res} - \epsilon \Phi_i)}{2\epsilon}$

Annexe 2 : impulse response of a FFWFS

- Impulse response of a FFWFS $IR = 2Im\left(\tilde{m}\left(m|\tilde{\mathbb{I}}_p|^2\right)\right)$ with m the phase mask and $FT(m) = \tilde{m}$
- Linear intensity expression : $\Delta I_{lin} = \mathbb{I}_p \Phi * IR$

ZWFS impulse response :

